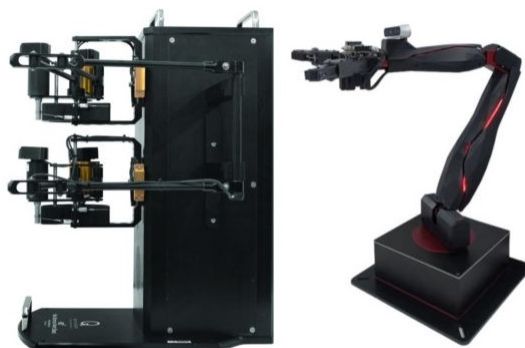




Quanser Telepresence System

Quanser's Telepresence System consists of a Quanser QArm manipulator along with a Quanser HD² High Definition Haptic Device. The open architecture design of the solution allows researchers to quickly develop and deploy emerging applications in telerobotics, telepresence, machine learning, assistive robotics, collaborative robotics, and more using MATLAB/Simulink. Quanser's QArm is a 4 DOF serial robotic manipulator with a tendon-based two-stage gripper and an RGBD camera, designed for modern engineering education and academic research applications. The HD² High-Definition Haptic Device is a high-fidelity haptic interface for advanced research in haptics and robotics.